

Projet réception GPS

Objectif :

Acquérir les trames GPS
Filtrer sur la trame GPRMC
Contrôler le checksum pour valider la trame reçue
Afficher sur LCD la date, l'heure et la vitesse :



Afficher la latitude et la longitude :



Ces données sont prélevées sur la trame GPRMC

Trames reçues toutes les secondes (entre deux traits rouges):

```
$GPGLL,4804.41218,N,00731.91033,E,071101.00,A,A*64CRLF
$GPRMC,071102.00,A,4804.41218,N,00731.91039,E,1.147,,271216,,,A*76CRLF
$GPUTG,,T,,M,1.147,N,2.125,K,A*24CRLF
$GPGGA,071102.00,4804.41218,N,00731.91039,E,1,05,2.42,182.4,M,47.3,M,,*56CRLF
$GPGSA,A,3,03,08,22,32,11,,,,,,,,,3.99,2.42,3.17*0ACRLF
$GPGSV,2,1,07,03,34,231,26,08,55,180,15,11,78,283,30,14,42,108,09*7ECRLF
$GPGSV,2,2,07,17,01,321,,22,52,230,31,32,39,072,19*4BCRLF
$GPGLL,4804.41218,N,00731.91039,E,071102.00,A,A*6DCRLF
$GPRMC,071103.00,A,4804.41186,N,00731.91104,E,1.406,,271216,,,A*7CCRLF
$GPUTG,,T,,M,1.406,N,2.604,K,A*20CRLF
$GPGGA,071103.00,4804.41186,N,00731.91104,E,1,05,2.42,182.3,M,47.3,M,,*5BCRLF
$GPGSA,A,3,03,08,22,32,11,,,,,,,,,3.99,2.42,3.17*0ACRLF
$GPGSV,2,1,07,03,34,231,26,08,55,180,15,11,78,283,30,14,42,108,08*7FCRLF
$GPGSV,2,2,07,17,01,321,,22,52,230,31,32,39,072,19*4BCRLF
$GPGLL,4804.41186,N,00731.91104,E,071103.00,A,A*67CRLF
$GPRMC,071104.00,A,4
```

Chaque trame commence avec le caractère \$

A la fin de la trame après le caractère étoile se trouve le checksum puis CR et LF

Le calcul du checksum se fait sur les caractères compris entre \$ et * (voir le détail du calcul dans le programme).

Trame GPRMC :

```
$GPRMC,094227.00,A,4804.40790,N,00731.91207,E,0.102,,261216,,,D*76
$GPRMC,094228.00,A,4804.40797,N,00731.91201,E,0.039,,261216,,,D*71
$GPRMC,094229.00,A,4804.40800,N,00731.91204,E,0.045,,261216,,,D*7F
```

```
GPRMC,094230.00,A,4804.40806,N,00731.91203,E,0.070,,261216,,,D*70
01234567890123456789012345678901234567890123456789012345678901234
```

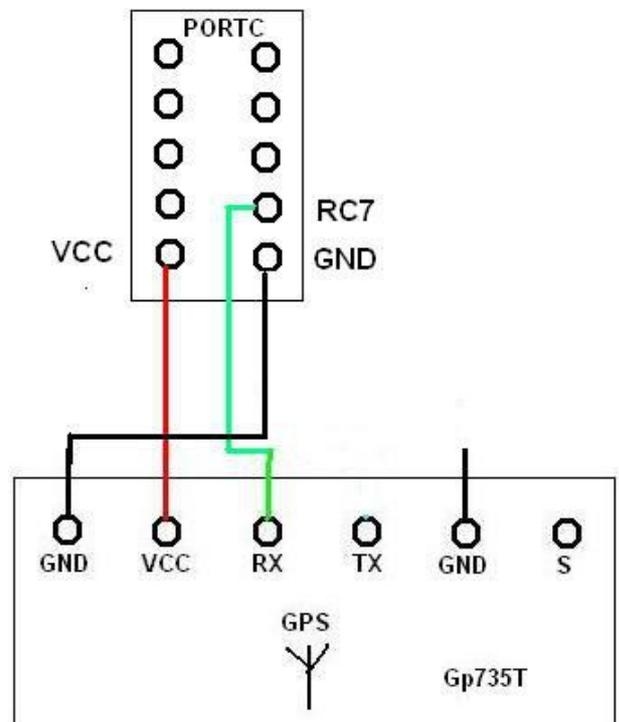
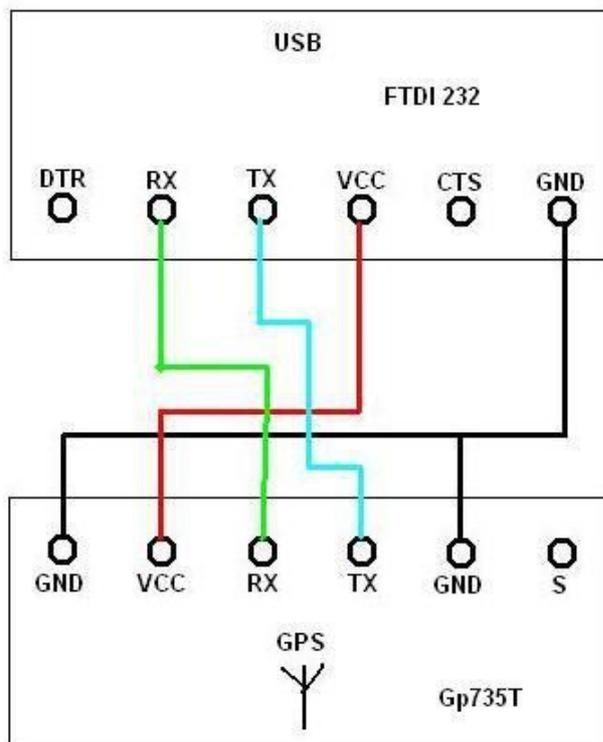
Matériel :

1 Récepteur GPS réf. GP-735-T (Chipset U-BLOX-7)

<http://www.lextronic.fr/P27906-recepteur-gps-oem-gp-735t.html>

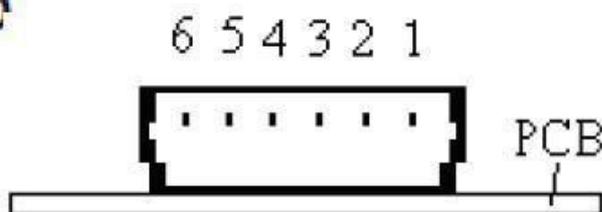
1 PIC18F2420 + afficheur LCD 2x16.

Branchement sur PC ou sur carte de développement EasyPic 5:



Branchement EasyPic 5

- 1 : GND
- 2 : VIN
- 3 : RX
- 4 : TX
- 5 : GND
- 6 : Directive



Programme PIC en Microbasic:

```

program TraceGps
'Ce programme reçoit les trames GPS, filtre la trame GPRMC et affiche les champs
'Heure, date, Latitude et Longitude.
'PIC 18F2420 Q=8MHz, récepteur GP735T SW7.RC7 = 1, SW8.RC6=1, Sw1.RA0=1,
'SW3.RC7=1 le 26/12/2016
'RCA.0 = 1 then affiche Date Heure Vitesse else affiche coordonnées Gps
'RCA.1 = 1 then Heure d'hiver else Heure d'été.
dim
  LCD_RS as sbit at RB4_bit
  LCD_EN as sbit at RB5_bit
  LCD_D7 as sbit at RB3_bit
  LCD_D6 as sbit at RB2_bit
  LCD_D5 as sbit at RB1_bit
  LCD_D4 as sbit at RB0_bit
dim
  LCD_RS_Direction as sbit at TRISB4_bit
  LCD_EN_Direction as sbit at TRISB5_bit
  LCD_D7_Direction as sbit at TRISB3_bit
  LCD_D6_Direction as sbit at TRISB2_bit
  LCD_D5_Direction as sbit at TRISB1_bit
  LCD_D4_Direction as sbit at TRISB0_bit

Dim Rec, Rec1 as string[74]
He as string[2] 'Extraction heure
HcW as word 'Heure corrigée en word
HcS as string[5] 'Heure corrigée en string
ScTime as string[8] 'HH:MM:SS
ScLat as string[11] 'Champs latitude
ScLon as string[12] 'Champ longitude
ScVit as string[5] 'Champ vitesse
ScDat as string[8] 'Champ date JJ/MM/AA
bc, i as integer
Tr as byte 'comptage trames
L1, L2 as string[16] 'Lignes LCD
ChS as string[2] 'cheksum lu en string
VitKmh as string[5] 'vitesse en kmh en string

'Procedure Interrupt RCI uart
  Sub procedure Interrupt
  if PIR1.RCIF = 1 then end if
  PIR1.RCIF = 0
  PIE1.RCIE = 0
end sub
'Fonction lecture RX Uart
sub function ReadChr as byte
do
loop until UART1_Data_Ready = 1
result=UART1_Read
end sub
'Fonction qui calcule le cheksum entre "$" et "*" et renvoi 0 si ok
sub function CtrlCs(dim byref Rec1 as string[64], dim byref ChS as string[4] ) as integer
dim ChSum as word
  Bc as integer
  ChSumTxt as string[4]

```

```

ChSum = 0 'word
for bc = 0 to 61
ChSum = ChSum xor ord(Rec1[Bc]+"" ) 'calcul
next bc
ChSumTxt = ""
wordtohex(ChSum,ChSumTxt)
result = StrCmp(ChSumTxt,ChS) 'compare cheksum calculé avec cheksum reçu
end sub

```

'Fonction conversion vitesse de noeud en kmh

```

sub function ConvVit(dim byref ScVit as string[5]) as string[5]
dim PosP as word 'Position du point décimal
'dim PospS as string[5]
dim Ve, Vd as string[5] 'Valeur entier et décimale en string
dim VeW, VdW as word 'Valeur entier et décimale en word
dim VF as float 'Vitesse en kmh en float
dim VFS as string[20] 'Vitesse en kmh en string
PosP = StrStr(ScVit, ".") 'Recherche position point décimal
if PosP = 1 then 'Si point en 1 (origine 0)
Ve = ScVit[0]+""
Vd = ScVit[2] + ScVit[3] + ScVit[4]
end if
if PosP = 2 then 'Si point en 2
Ve = ScVit[0] + ScVit[1]
Vd = ScVit[3] + ScVit[4]
end if
if PosP = 3 then 'Si point en 3
Ve = ScVit[0] + ScVit[1] + ScVit[2]
Vd = ScVit[4]+""
end if
VeW = strtoword(Ve) 'Conversion valeur entiere en word
VdW = strtoword(Vd) 'Conversion valeur décimale en word
if PosP = 1 then VF = (float(VeW) + (float(VdW) /1000))*1.852 end if
if PosP = 2 then VF = (float(VeW) + (float(VdW) /100))*1.852 end if
if PosP = 3 then VF = (float(VeW) + (float(VdW) /10))*1.852 end if
floattostr(VF,VFS)
result = VFS[0]+VFS[1]+VFS[2]+VFS[3]+VFS[4] '5 premiers caractere
end sub

```

main:

```

UART1_INIT(9600)
ADCON1 = $0F '
CMCON = 7
INTCON.IPEN = 1 'Compateur off
PIE1.RCIE = 0
INTCON.PEIE = 1
INTCON.GIE = 1
PORTA = $0
PORTB = $0
PORTC = $0
TRISA = %00000011
TRISB = %00000000
TRISC = %10000000
LCD_Init()
Lcd_Cmd(_LCD_CLEAR) ' Clear display
Lcd_Cmd(_LCD_CURSOR_OFF) ' Cursor off

```

```

LCD_Out(1,1," RECEPTION GPS ")
Delay_ms(2500)
While true
'Lecture des trames
Rec = ""
Rec1 = ""
Tr = 0
do
do
i=ReadChr      ' fonction lecture uart byte à byte
loop until i=36  ' detection début de trame si "$" reçu
i=0
do
Rec[i]=ReadChr      ' fonction lecture uart byte à byte
if Rec[i]= chr(10) then ' init compteur de caracteres
i=0
else
i=i+1
end if
loop until (i=0)      ' detection début de trame avec "$"
if ((Rec[2]="R") and (Rec[3]="M") and (Rec[4]="C")) then ' Fitre sur RMC (GPRMC)
i=0
do
Rec1=Rec1 + char(Rec[i]) 'Création trame GPRMC
i=i+1
loop until (i=0) or Rec[i]=chr(10) ' detection fin de trame
end if
inc(Tr)
loop until Tr =7 ' laisser passer 7 trames
'uart1_write_text(Rec2)

```

```

'Heure
ScTime = ""
He=Rec1[6]+Rec1[7]
HcW=strtoword(He)
if HcW<23 then
if TestBit(PORTA,1) = 1 then HcW=HcW+1 else HcW=HcW+2 end if
else
HcW=0
end if
wordtostr(HcW,HcS)
Ltrim(HcS)
if HcW<10 then HcS="0"+HcS end if 'correction UTC
ScTime = HcS+":"+Rec1[8]+Rec1[9]+":"+Rec1[10]+Rec1[11]

```

```

'Latitude
ScLat=""
for Bc = 18 to 27
ScLat = ScLat+Rec1[Bc]
next Bc
ScLat=ScLat+Rec1[29]

```

```

'Longitude
ScLon=""
for Bc = 31 to 41
ScLon = ScLon+Rec1[Bc]
next Bc

```

```

    ScLon=ScLon+Rec1[43]
'Vitesse
    ScVit=""
    for Bc = 45 to 49
    ScVit = ScVit+Rec1[Bc]
    next Bc
    VitKmh = ConvVit(ScVit) 'Conversion vitesse de noeud en kmh
'Date
    ScDat=""
    ScDat=Rec1[52]+ Rec1[53]+"/"+ Rec1[54]+Rec1[55]+"/"+Rec1[56]+Rec1[57]
'Cheksum lu
    ChS = "00"+Rec1[63]+ Rec1[64] 'chekssum reçu
'Affichage LCD
if Rec1[16] = "A" then
    if CtrlCs(Rec1,ChS) = 0 then 'si cheksum (Rec1[0] à Rec1[61]) = 1
        if TestBit(PORTA,0)=1 then
            Lcd_Out(1,1, ScDat +" V=" + VitKmh)
            Lcd_Out(2,1,ScTime +" ")
        else
            L1 = " "+ScLat[0]+ScLat[1]+Chr($DF) +ScLat[2]+ScLat[3]+"""+
ScLat[5]+ScLat[6]+ScLat[7]+ScLat[8]+ScLat[9]+" "+ScLat[10]
            Lcd_Out(1,1,L1 + " ")
            L2 = " "+ScLon[0]+ScLon[1]+ScLon[2]+Chr($DF) +ScLon[3]+ScLon[4]+"""+
ScLon[6]+ScLon[7]+ScLon[8]+ScLon[9]+ScLon[10]+" "+ScLon[11]
            Lcd_Out(2,1,L2 + " ")
        end if
    end if
else
    Lcd_Out(1,1," Recherche ")
    Lcd_Out(2,1," Satelites ")
end if
wend
end.

```