

Formules – PHS0102

<u>Constantes</u>	
$k = \frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \text{ N}\cdot\text{m}^2/\text{C}^2$	$m_p = 1,672 \times 10^{-27} \text{ kg}$
$\epsilon_0 = 8,85 \times 10^{-12} \text{ F/m}$	$m_e = 9,109 \times 10^{-31} \text{ kg}$
$\mu_0 = 4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}$	$e = 1,602 \times 10^{-19} \text{ C}$
	$1 \text{ eV} = 1,602 \times 10^{-19} \text{ J}$
<u>Mécanique</u>	
$v_x = v_{0x} + a_x t$	$\sum \vec{F} = m\vec{a}$
$x = x_0 + \frac{1}{2}(v_{0x} + v_x)t$	$K = \frac{1}{2}mv^2$
$x = x_0 + v_{0x}t + \frac{1}{2}a_x t^2$	$\Delta K + \Delta U = W_{ext}$
$v_x^2 = v_{0x}^2 + 2a_x(x - x_0)$	
$a_r = v^2/r$	$P = \frac{dU}{dt}$
<u>Électrostatique</u>	
$\vec{F}_{12} = \frac{kQ_1Q_2}{r_{21}^2} \vec{u}_{r_{21}}$	$V = k \frac{Q}{R}$
$\vec{F} = Q\vec{E}$	$\Delta V = V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{s} = \pm Ed$
$\vec{E} = \frac{kQ}{r^2} \vec{u}$	$\lambda = Q/L ; \sigma = Q/A ; \rho = Q/V$
$V = \frac{U}{q}$	$\phi_E = \oint \vec{E} \cdot d\vec{A} = Q_{int}/\epsilon_0$
<u>Circuits DC</u>	
$C = \frac{Q}{\Delta V}$	$C_{plan} = \frac{\epsilon_0 A}{d}$
$\frac{1}{C_{\acute{e}q}} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_N}$	$I = \frac{dQ}{dt} = nAev_d$
$C_{\acute{e}q} = C_1 + C_2 + \dots + C_N$	$R = \frac{\rho \ell}{A}$
$C_D = \kappa C_0$	$\Delta V = RI$
$U_E = \frac{1}{2}Q\Delta V = \frac{Q^2}{2C} = \frac{1}{2}C\Delta V^2$	$P = I \Delta V = RI^2 = \frac{\Delta V^2}{R}$

Circuit DC (suite)

$$R_{\acute{e}q} = R_1 + R_2 + \dots + R_N$$

$$\frac{1}{R_{\acute{e}q}} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_N}$$

$$\sum_{\text{noeud}} I = 0$$

$$\sum_{\text{maille}} \Delta V = 0$$

$$\rho = \rho_0 [1 + \alpha(T - T_0)]$$

$$Q = Q_0 e^{-t/\tau}$$

$$Q = Q_0 (1 - e^{-t/\tau})$$

$$I = I_0 e^{-t/\tau}$$

$$\tau = RC$$

Magnétisme

$$\vec{F}_B = q\vec{v} \times \vec{B}$$

$$F_B = |q|vB \sin \theta$$

$$\vec{F}_B = I\vec{\ell} \times \vec{B}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$r = \frac{mv}{|q|B}$$

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\frac{F}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi d}$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$$

$$B = \mu_0 nI$$

$$B = \mu_0 NI / 2\pi r$$

Induction

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$

$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

$$N\Phi_B = LI$$

$$\mathcal{E}_L = -L \frac{dI}{dt}$$

$$I = I_0 (1 - e^{-t/\tau})$$

$$I = I_0 e^{-t/\tau}$$

$$\tau = L/R$$

$$U_L = \frac{1}{2} LI^2$$

Circuits AC

$$i(t) = I_0 \sin(\omega t)$$

$$\Delta v(t) = \Delta V_0 \sin(\omega t + \phi)$$

$$I_{\text{eff}} = \frac{I_0}{\sqrt{2}} ; \quad \Delta V_{\text{eff}} = \frac{\Delta V_0}{\sqrt{2}}$$

$$\Delta V_0 = ZI_0 ; \quad \Delta V_{\text{eff}} = ZI_{\text{eff}}$$

$$Z = \sqrt{R^2 + (Z_L - Z_C)^2}$$

$$Z_L = \omega L$$

$$Z_C = 1/\omega C$$

$$\omega_0 = 1/\sqrt{LC}$$

$$\tan \phi = \frac{Z_L - Z_C}{R}$$

$$p(t) = i(t) \cdot \Delta v(t)$$

$$P_{\text{eff}} = RI_{\text{eff}}^2 = I_{\text{eff}} \Delta V_{\text{eff}} \cos \phi$$